# A Convergence-Improving Iterative Method for Computing Periodic Orbits near Bifurcation Points 

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#### Abstract

The accurate computation of periodic orbits and the precise knowledge of their bifurcation properties are very important for studying the behavior of many dynamical systems of physical interest. In this paper, we present an iterative method for computing periodic orbits, which has the advantage of improving the convergence of previous Newton-like schemes, especially near bifurcation points. This method is illustrated here on a conservative, nonlinear Mathieu equation, for which a sequence of period-doubling bifurcations is followed, long enough to obtain accurate estimates of the two universal scaling constants $\alpha, \beta$, as well as the universat rate $\delta$, by which the bifurcation values of a parameter $q=q_{k}, k=1,2,3, \ldots$, tend to their limiting value, $q_{x}<\infty$, as $k$ increases. © 1990 Academic Press, Inc.


## 1. Introduction

In recent years, it has been widely recognized that even the simplest noninear dynamical systems of the form

$$
\begin{equation*}
\dot{\mathbf{x}}=\frac{d \mathbf{x}}{d t}=\mathbf{f}(\mathbf{x}, t), \quad \mathbf{x}=\left(x_{1}, \ldots, x_{n}\right) \tag{1.1}
\end{equation*}
$$

can have solutions (or orbits) $\mathbf{x}(t)$, with remarkable properties. Perhaps the mosi remarkable of them all is that, for large classes of initial conditions $\mathbf{x}(0)$, the orbits of (1.1) behave, as $t \rightarrow \infty$, in an apparently unpredictable, irregular or, as is more commonly called, chaotic way [1-5].

These chaotic orbits are located near unstable (hyperbolic) fixed points and periodic orbits, and are present at all scales, when (1.1) describes a non-integrable Hamiltonian system [5,6]. On the other hand, again in the Hamiltonian case,
around the stable (elliptic) periodic orbits there are "islands" of regular behavior whose size is larger, the smaller the period of the orbit [5-7].

In fact, periodic orbits are "dense" among all orbits of a Hamiltonian systems and-as Poincaré himself had suggested [8]-by studying them, one can understand some of the more "global" properties of the motion of dynamical systems [6-10].

In this paper, we present a rapidly convergent algorithm for calculating periodic orbits by computing iteratively, and to any desired accuracy, the coefficients $A_{n}$ of their Fourier series expansions. This algorithm becomes especially significant near bifurcation points, where new periodic orbits appear, and other more traditional approaches (like Newton's method, etc.) cannot easily distinguish among the closely neighboring roots of the associated nonlinear algebraic equations for the $A_{n}$ 's.

Here we shall illustrate this method on the equation

$$
\begin{equation*}
\ddot{x}+(1+2 q \cos 2 t) x-x^{3}=0 \tag{1.2}
\end{equation*}
$$

derived from the Hamiltonian

$$
\begin{equation*}
H=\frac{1}{2}\left(\dot{x}^{2}+\dot{x}^{2}\right)-\frac{1}{4} x^{4}+q x^{2} \cos 2 t \tag{1.3}
\end{equation*}
$$

by studying its main sequence of period-doubling bifurcations of periodic orbits with period $T_{k}=2^{k} \pi, k=1,2, \ldots$ as the parameter $q>0$ in (1.2) is increased. The importance of such period doubling sequences as "routes" towards large scale chaotic behavior, in Hamiltonian as well as dissipative systems, has been amply discussed in the recent literature [2-5] and need not be repeated here.

It must be pointed out, however, that the method we shall describe in this paper represents a definite improvement over an iterative-variational method introduced by Eminhizer et al. [9] and Helleman and Bountis [6] to obtain periodic solutions of dynamical systems like (1.2). It is an improvement in the sense that it converges more rapidly than Helleman's Newton-like scheme [10], when applied to the period-doubling bifurcations of (1.2). The main reason behind this improvement is that our method of "root-searching" is not affected by a Jacobian taking small values in between neighboring roots, while Newton's method is notorious for breaking down precisely in that case.

Thus, we start in the next section by reviewing Budinsky's application of the more usual iterative Fourier schemes to the period-doubling bifurcations of Eq. (1.2) [7]. We also outline there briefly her stability analysis using Hill's determinants and discuss the accuracy limitations encountered already in determining the third bifurcation, i.e., that of the period 8 (in units of $\pi$ ) orbit out of the orbit of period 4.

Then, in Section 3, we describe our method for solving the nonlinear algebraic equations of Section 2 (for the Fourier coefficients $A_{n}$ of these orbits) and present our results for the bifurcations of period 4 , period 8 , and period 16 orbits. Denoting
by $q_{k}$ the value of $q$ at which the orbit of period $2^{k}$ appears, we compute, in Section 4, to high accuracy the ratios

$$
\begin{equation*}
\delta_{k}=\left(q_{k}-q_{k+1}\right) /\left(q_{k+1}-q_{k+2}\right), \quad k=1,2,3, \ldots \tag{1.4}
\end{equation*}
$$

and verify that they quickly tend to the universal number $\delta=8.7210972$... [ $11,12,3,4]$ as $k$ increases.

Morcover, in Scetion 4, we compute the first approximations of the universal scaling constant,

$$
\begin{equation*}
\alpha=\lim _{n \rightarrow \infty} \frac{d_{n}}{d_{n+1}}=4.0180767 \ldots, \tag{1.5}
\end{equation*}
$$

where $d_{n}$ is the distance of the two nearest points of a periodic orbit of period $2^{n}$ (when it bifurcates to a period $2^{n+1}$ orbit), as well as approximations of the second universal scaling constant $\beta=16.36389 \ldots$ [12]. All these values turn out to agree very well with those given in the literature $[11,12]$ for area-preserving mappings in the plane.

We finally end, in Section 5, with some concluding remarks on the applicability of our methods to the bifurcation properties of periodic orbits of more general dynamical systems.

## 2. An Iterative Fourier Method for Period-Doubling Bifurcations

In this section, we describe an iterative Fourier scheme for obtaining periodic solutions of the nonlinear Mathieu equation

$$
\begin{equation*}
\ddot{x}+(1+2 q \cos 2 t) x-x^{3}=0 \tag{2.1}
\end{equation*}
$$

of period $T_{k}=2^{k} \pi, k=1,2,3, \ldots$. These solutions (or, orbits) bifurcate out of one another at the values $q_{k}$, with $0<q_{1}<q_{2}<\cdots<q_{\infty}<\infty$, at which the orbit of period $T_{k-1}$ destabilizes and gives "birth" to a stable orbit of period $T_{k}$.

At $q=0$, the origin of the phase plane $x, \dot{x}$ is a stable fixed point, surrounded by "clliptic" closed curves, as depicted schematically in Fig. 1a. At $0<q \ll 1$, this point has become unstable and a stable period 2 (in units of $\pi$ ) orbit has appeared, intersecting at the points $I_{1}, I_{2}$ the surface of section [1-4],

$$
\begin{equation*}
\sum_{0}=\left\{\left(x\left(t_{n}\right), \dot{x}\left(t_{n}\right)\right) / t_{n}=n \pi, n \in Z\right\} \tag{2.2}
\end{equation*}
$$

see Fig. 1b.
Following these points by solving (2.1) numerically (e.g., by a standard Runge Kutta-type scheme) one finds that they turn unstable at

$$
\begin{equation*}
q=q_{1}=0.501041950415 \tag{2.3}
\end{equation*}
$$



Fig. 1. A schematic drawing of the intersections of orbits of the nonlinear Mathieu equation (2.1) with the $x, \dot{x}$ surface of Section (2.2), at $t=n \pi, n=0,1,2,3 \ldots$ : (a) $q=0$, the integrable case, where all orbits lie on the plane; (b) $0<q \ll 1$, where there is a stable period $2 \pi$ orbit labeled by I ; (c) $q=0.51$, where orbit I has destabilized and given "birth" to the stable period $2 \pi$ orbits II and III; (d) $q=0.526$, where orbits II and III have also turned unstable, yielding two stable period $4 \pi$ orbits.
giving rise to a pair of period 2 orbits, labeled by II and III in Fig. 1c, which are not each symmetric w.r.t. the $\dot{x}$ axis, but do possess this symmetry w.r.t. each other (Note that due to the form of Eq. (2.1), if $x(t), \dot{x}(t)$ is a solution, then so is $-x(-t), \dot{x}(-t)$.)

We may thus follow one of these period 2 orbits (e.g., the one labeled by II) and find that it also destabilizes at

$$
\begin{equation*}
q_{1}<q_{2}=0.5250750359375 \tag{2.4}
\end{equation*}
$$

(as does orbit III, of course) but in a rather peculiar way: Point $\mathrm{II}_{1}$ splits into two "islands" along the $x$-axis, while $\mathrm{II}_{2}$ into two much thinner islands nearly vertically "off" the horizontal axis, see Fig. 1d. This is precisely the period-doubling scenario obscrved in conservative models of two degrees of freedom [11, 12] occurring in much the same way as Feigenbaum discovered first for one-dimensional systems [13].

Of course, by the time period 4 orbits have appeared at $q=q_{2}$, large scale chaos has already spread in phase space, as shown schematically in Figs. 1c, d. Even though this is the typical situation, it is still interesting to develop methods to further pursue period-doubling bifurcations for several reasons: First, much less is known about their general properties in higher-dimensional systems [14, 15]. Second, there are similar bifurcation phenomena of orbits of much longer period which occur while there is still large scale regular motion in phase space And finally, one may wish to accurately verify certain universality properties, which are expected to hold as $k \rightarrow \infty$, or $q \rightarrow q_{\infty}<\infty$.

In any case, to construct periodic orbits of Eq. (2.1) as convergent Fourier series of the form

$$
\begin{equation*}
x(t)=\sum_{n=-\infty}^{\infty} A_{n} e^{i n v_{r} i}, \quad A_{n}^{*}=A_{-n} \tag{2.5}
\end{equation*}
$$

one starts by specifying the important "winding" or "rotation number" $\sigma[6,9,10]$ defined by

$$
\begin{equation*}
\sigma=m_{1} / m_{2}=v_{1} / v_{2} \tag{2.6}
\end{equation*}
$$

as the ratio of two fundamental frequencies of the problem

$$
\begin{equation*}
v_{1}=m_{1} v_{r}, \quad v_{2}=m_{2} v_{r}, \tag{2.7}
\end{equation*}
$$

where $m_{1}, m_{2}$ are positive integers and $v_{r}$ is the recurrence (or, actual) frequency of the orbit.

In the case of our period-doubling sequence of orbits with period

$$
\begin{equation*}
T_{k}=2^{k} \pi, \quad v_{r}=2^{1-k}, \quad k=1,2,3, \ldots \tag{2.8}
\end{equation*}
$$

the second frequency of the problem $v_{2}=2$, i.e., is that of the periodic driving term in (2.1), and hence $m_{2}=2^{k}$ is known for each orbit, cf. (2.7), (2.8). Moreover, since the period $2^{k}$ orbit intersects the surface of Section (2.2) $m_{2}$ times, "rotating" around the origin $m_{1}$ times, its $m_{1}=2^{k-1}$ value is also known. Thus, expecting that the main Fourier coefficient in (2.5) will be $A_{m_{1}}$, one may write (2.1) as a forced harmonic oscillator of frequency $v_{1}$,

$$
\begin{equation*}
\ddot{x}+v_{1}^{2} x=v_{1}^{2} x-(1+2 q \cos 2 t) x+x^{3} \tag{2.9}
\end{equation*}
$$

and substitute all of the above in (2.9) to obtain a recursion relation for the $A_{n}$ 's [7],
$\left(m_{1}^{2}-n^{2}\right) v_{r}^{2} A_{n}^{\prime}=\left(v_{1}^{2}-1\right) A_{n}+\sum_{n_{1}+n_{2}+n_{3}=n} A_{n_{1}} A_{n_{2}} A_{n_{3}}-q\left(A_{n+m_{2}}+A_{n-m_{2}}\right)$
which are to be solved for the $A_{n}$ 's from the 1 .h.s. This can be done for all $n$ except $n=m_{1}$, for which either the $A_{m_{1}}$ is solved from the r.h.s. of (2.10) or, one scales the
$A_{n}$ 's by defining $B_{n}=A_{n} / x(0)$ and solves the $n=m_{1}$ equation for the initial condition $x(0)$, obtaining $B_{m_{1}}$ from the $t=0$ equation

$$
\begin{equation*}
1=B_{0}+\sum_{n=-\infty}^{\infty} B_{n} \tag{2.11}
\end{equation*}
$$

This program was carried out in [7] and the periodic orbits of period 2, 4, and 8 were convergently obtained, but not without making one further modification: A term of the form $\beta A_{n}$ had to be added to both sides of (2.10), where $\beta$ was a suitably chosen constant. Moreover, in the case of period $8, \beta$ had to be assigned different values $\beta_{1}$ and $\beta_{2}$ for the iteration of the even and odd $n$ coefficients, respectively. Still, despite these modifications, the $A_{n}$ 's for period 8 could only be calculated with limited accuracy that prevented a satisfactory calculation, e.g., of the universal rates of this problem [7].

Now, as it has been argued elsewhere [10], the above iteration scheme can converge quadratically, i.e., is Newton-like, provided the initial values of the $A_{n}$ 's are "close enough" to the final ones. And what if there are several possibilities of "final" values ncarby, as it docs happen just beyond a bifurcation point? This is exactly where a Newton-like scheme becomes problematic and a new iterative method needs to be introduced-like the one described in the next section-which will circumvent the convergence problems mentioned above.

Before describing this new method, however, and its results, we end this section with a brief discussion of how the knowledge of the Fourier coefficients $A_{n}$ can be used to study the stability properties of the associated periodic orbit. This is done using Floquet theory and Hill's determinants [ 16,17$]$ in the following way: Suppose we want to determine the stability of a periodic orbit $\hat{x}(t)$ of the form (2.5). We first linearize Eq. (2.1) about this orbit, substituting $x=\hat{x}+z(t)$ and dropping $O\left(z^{2}\right)$ terms to find

$$
\begin{equation*}
\ddot{z}(t)+\left[1+2 q \cos 2 t-3 \hat{x}^{2}\right] z(t)=0 . \tag{2.12}
\end{equation*}
$$

This is a Hill's equation [17] of the type

$$
\begin{equation*}
\ddot{z}(t)+Q(t) z(t)=0 \tag{2.13}
\end{equation*}
$$

with $Q(t)=Q\left(t+2 \pi / v_{r}\right)$, also expressed as a Fourier series

$$
\begin{equation*}
Q(t) \equiv 1+2 q \cos 2 t-3 \hat{x}^{2}=\sum_{n=-\infty}^{\infty} a_{n} e^{i n v_{r} t} \tag{2.14}
\end{equation*}
$$

and $a_{n}$ 's given explicitly in terms of the known $A_{n}$ 's of (2.5) by

$$
\begin{equation*}
a_{n}=\delta_{n, 0}+q\left(\delta_{n, m_{2}}+\delta_{n,-m_{2}}\right)-3 \sum_{k=-\infty}^{\infty} A_{k} A_{n-k} \tag{2.15}
\end{equation*}
$$

Now, the general solution of (2.13) is given by a linear combination of its fundamental solutions $z_{ \pm}(t)=\exp ( \pm i \mu t) P_{ \pm}(t)$, where $P_{ \pm}(t)=P_{ \pm}\left(t+2 \pi / v_{r}\right)$ and $\mu$ is the so-called Floquet exponent $[16,17]$. Thus, the boundedness (or unboundedness) of $z(t)$, and hence the stability (or, instability) of the periodic orbit $\hat{x}(t)$, depends on whether the Floquet exponent $\mu$ is real (or, imaginary). For an orbit of frequency $\nu_{r}$, cf. (2.8), this is decided finally by the criterion [16]:

$$
\left|S_{k}\right| \equiv\left|1-2 \sin ^{2}\left(2^{k-1} \pi \sqrt{a_{0}}\right) \operatorname{det} \mathbf{D}\right|\left\{\begin{array}{l}
<1: \text { Stability }  \tag{2.16}\\
>1: \text { Instability }
\end{array}\right.
$$

$k=1,2, \ldots$, where $\mathbf{D}$ is the Hill's matrix, with elements

$$
D_{m, n}=a_{n-m} /\left(a_{0}-n^{2} v_{r}^{2}\right), \quad n \neq m
$$

and

$$
\begin{equation*}
D_{m, m}=1, \quad n, m=-\infty, \ldots, \infty \tag{2.17}
\end{equation*}
$$

Thus, the bifurcation values $q_{k}$, like $q_{1}$ and $q_{2}$ of (2.3) and (2.4), are computed as follows: At $q=q_{1}, S_{1}=1$, whereupon it starts to decrease reaching -1 at $q=q_{2}$. Then, we evaluate $S_{2}$ using the coefficients of the period 4 orbit and determine $q_{3}$ from:

$$
\begin{equation*}
1 \geqslant S_{2} \geqslant-1: \quad q_{2} \leqslant q \leqslant q_{3}=0.527780774375 \tag{2.18}
\end{equation*}
$$

However, due to limited accuracy in the calculation of the $A_{n}$ 's of the period 8 orbit, $q_{4}$ could only be computed to 4 -digit accuracy by the methods of this section. We, therefore, turn now to the new method of this paper to overcome these convergence difficulties and compute to the desired precision the bifurcations at $q=q_{4}, q_{5}$, etc.

## 3. A New Iterative Scheme with Improved Convergence

In order to circumvent the convergence difficulties of the Newton-like schemes of the previous section, we shall introduce here a new iterative method for solving the nonlinear algebraic equations (2.10). This method, which we call nonlinear successive overrelaxation bisection method (NSORB), is an extension of the wellknown generalized linear iterative methods $[18,19]$ and has the advantage of not being affected by variations in the magnitude of the Jacobian, which is primarily what plagues the convergence rate of Newton schemes near bifurcation points.

Below, we briefly describe the main steps of the NSORB method. More details, convergence proofs, and further applications will be published elsewhere [20]. Suppose we have to solve a system of nonlinear algebraic equations

$$
\begin{equation*}
f_{i}(\mathbf{x})=0, \quad \mathbf{x}=\left(x_{1}, \ldots, x_{N}\right), \quad i=1,2, \ldots, N \tag{3.1}
\end{equation*}
$$

with $f_{i}: \mathbb{R}^{N} \rightarrow \mathbb{R}$ continuous. Starting with the initial choice,

$$
\begin{equation*}
\mathbf{x}^{0}=\left(x_{1}^{0}, x_{2}^{0}, \ldots, x_{N}^{0}\right) \tag{3.2}
\end{equation*}
$$

we shall obtain estimates $\mathbf{x}^{k}, k=1,2, \ldots$, of the solution $\mathbf{x}$ of Eq. (3.1) by solving, at the $k$ th step, for the component $x \equiv x_{i}^{k+1}$, from the equation

$$
\begin{equation*}
g_{i}(x)=f_{i}\left(x_{1}^{k}, \ldots, x_{i-1}^{k}, x, x_{i+1}^{k}, \ldots, x_{N}^{k}\right)=0 \tag{3.3}
\end{equation*}
$$

We then set the following, using a relaxation parameter $\omega \in(0,1]$,

$$
\begin{equation*}
x_{i}^{k+l}=x_{i}^{k}+\omega\left(x-x_{i}^{k}\right), \quad i=1, \ldots, N, \quad k=0,1, \ldots, \tag{3.4}
\end{equation*}
$$

and compute $x$, performing $m$-steps of the following modified one-dimensional bisection method [21-24],

$$
\begin{equation*}
x_{\lambda+1}=x_{\lambda}+\operatorname{sgn} g_{i}\left(x_{i}^{0}\right) \operatorname{sgn} g_{i}\left(x_{\lambda}\right) h_{i} / 2^{\lambda+1}, \quad \lambda=0,1,2, \ldots, m-1 \tag{3.5}
\end{equation*}
$$

cf. (3.3), where $\operatorname{sgn} \Theta$ is the well-known sign function,

$$
\operatorname{sign} \Theta=\left\{\begin{align*}
-1, & \text { if } \Theta<0  \tag{3.6}\\
0, & \text { if } \Theta=0 \\
1, & \text { if } \Theta>0
\end{align*}\right.
$$

and $h_{i}$ is such that

$$
\begin{equation*}
\operatorname{sgn} g_{i}\left(x_{i}^{0}\right) \cdot \operatorname{sgn} g_{i}\left(x_{i}^{0}+h_{i}\right)=-1 \tag{3.7}
\end{equation*}
$$

It is easy to check that the above iterative scheme converges to the value of $x$ that satisfies (3.3). Moreover, it can be shown that the number of iterations $m$ needed to obtain $x$, from (3.5), with accuracy $\varepsilon$, is given by [21-24]

$$
\begin{equation*}
m=\left\lceil\log _{2}\left(h_{i} \varepsilon^{-1}\right)\right\rceil \tag{3.8}
\end{equation*}
$$

where $\lceil a\rceil$ denotes the least positive integer that is not smaller than the real number $a$. Also, the convergence of the iterates of (3.3)-(3.4) is similar to the convergence of the class of generalized linear iterative methods [18, 19], since these belong to that class. Finally, instead of the Jacobi iterations (3.3)-(3.4) we can use the relative Gauss-Seidel iterations. Thus, rather than solving Eq. (3.3), we can solve the following equation in the same manner,

$$
g_{i}(x)=f_{i}\left(x_{1}^{k+1}, \ldots, x_{i-1}^{k+1}, x, x_{i+1}^{k}, \ldots, x_{N}^{k}\right)=0
$$

The $m$-step NSORB method described above is particularly suited for problems (3.1) whose zeroes are very close to each other, since, in that case, it is well known that Newton-like schemes do not always converge to the desired solution, even for initial points starting close to it. Thus, the NSORB method turns out to be
especially useful near bifurcation points, where different periodic orbits coexist, within very small distances from each other in phase space, and correspond to different solutions $\left\{A_{n}, n=0,1,2, \ldots\right\}$ of the system

$$
\begin{equation*}
\left(1-n^{2} v_{r}^{2}\right) A_{n}+q\left(A_{n+m_{2}}+A_{n-m_{2}}\right)-\sum_{n_{1}+n_{2}+n_{3}=n} \sum_{n_{1}} A_{n_{2}} A_{n_{3}}=0 \tag{3.9}
\end{equation*}
$$

cf. (2.10). This is particularly true if the bifurcated "daughter" periodic orbit has the same or double the period of the "mother" orbit, since then both orbits have $A_{n}$ 's that satisfy equations (3.9), with the same $v_{r}$. In period-doubling, for example, the "mother" orbit can always be recovered, at the $v_{r}$ of its "daughter," by setting all the odd $n$ coefficients $A_{n}$ of the "daughter" orbit equal to zero.

Furthermore note that, with the proper choice of $h_{i}$ in (3.5), it is possible to isolate a solution of (3.3) (or (3.9)) without the necessity of a good initial estimate (3.2). Finally, since in the various function evaluations, only the signs of these functions need to be correct, the NSORB method can be applied to problems where the actual values of these functions are not known to great precision.

We now proceed to discuss the results of the application of the NSORB method to the period-doubling bifurcations of Eq. (2.1) discussed in the previous section: As a starting point, we began by evaluating, at different values of $q$, the Fourier coefficients of the periodic orbit II of period 2, as well as the cocfficients of the period 4 and period 8 orbits that bifurcate out of it (see Figs. 1c, d).

The first 16 of these coefficients are listed below in Table I. They correspond, respectively, to $q$ values, at which these orbits are ready to bifurcate to their "daughter" periodic orbits of twice the period and have been obtained (to an accuracy of $10^{-15}$ ) by iterating Eqs. (3.3)-(3.5) some $50-60$ times on a personal computer.

Observe that, as expected from period-doubling bifurcations of other dynamical systems [1-5], these orbits intersect the surface of Section (2.2) at closely neighboring points. This can be verified here by using the obtained $A_{n}$ 's to substitute in the Fourier series (2.5) at $t=k \pi$, with $v_{r}=1,1 / 2$, and $1 / 4$ for the three periodic orbits of Table I. Note the close proximity of their $A_{0}$ values, and the values of the important coefficients $A_{1}, A_{2}$, and $A_{4}$ of the period $2 \pi, 4 \pi$, and $8 \pi$ orbits, respectively.

Observe, more generally, how the $A_{n}$ values of these orbits compare, for $n$ even; As predicted by the theory [25], the $A_{n}$ values of one orbit are very close to the $A_{2 n}$ values of the orbit that has bifurcated out of it. Thus, even though the magnitude of the $A_{n}$ 's generally decreases rapidly with increasing $n$, as the period of the orbit gets higher, large $A_{n}$ 's will appear at higher and higher $n$ (see, e.g., the $A_{12}$ coefficient of period $8 \pi$ ). This implies that an accurate computation of higher period orbits, by this method, requires the knowledge of an exponentially growing number of Fourier coefficients $A_{n}$. Since, according to the above remarks, the magnitude of these coefficients does not significantly change with increasing period, one can estimate the truncation index $n_{\max }$ necessary to achieve a desired accuracy.

TABLE I

|  | Period $2 \pi$ (II) orbit | Period $4 \pi$ orbit | Period $8 \pi$ orbit |
| :---: | :---: | :---: | :---: |
| $q$ | 0.5250750359375 | 0.527780774375 | 0.528089535489 |
| $A_{0}$ | -0.101079850572 | -0.102084233567 | -0.102478551216 |
| $A_{1}$ | 0.405880573247 | $0.112950375934 \mathrm{E}-1$ | $-0.205457274490 \mathrm{E}-2$ |
| $A_{2}$ | $0.215024973106 \mathrm{E}-3$ | 0.406432413099 | $0.114319030915 \mathrm{E}-1$ |
| $A_{3}$ | $0.162272390174 \mathrm{E}-1$ | $0.120475694919 \mathrm{E}-2$ | $-0.752684006155 \mathrm{E}-3$ |
| $A_{4}$ | $0.249351465912 \mathrm{E}-3$ | $0.144233907811 \mathrm{E}-3$ | 0.406442830989 |
| $A_{5}$ | $0.974953318166 \mathrm{E}-5$ | $0.416106833246 \mathrm{E}-4$ | $-0.272002262271 \mathrm{E}-3$ |
| $A_{6}$ | $0.194410572006 \mathrm{E}-5$ | $0.163382954916 \mathrm{E}-1$ | $0.122135978580 \mathrm{E}-2$ |
| $A_{7}$ | $-0.648782646554 \mathrm{E}-5$ | $-0.286450436909 \mathrm{E}-4$ | $-0.351572017672 \mathrm{E}-4$ |
| $A_{8}$ | $-0.180318836485 \mathrm{E}-6$ | $0.253321521252 \mathrm{E}-3$ | $0.136194204310 \mathrm{E}-3$ |
| $A_{9}$ | $-0.581424467648 \mathrm{E}-7$ | $-0.223803586696 \mathrm{E}-4$ | $-0.546269657348 \mathrm{E}-5$ |
| $A_{10}$ | $-0.348385768741 \mathrm{E}-8$ | $0.106143802603 \mathrm{E}-4$ | $0.425123798715 \mathrm{E}-4$ |
| $A_{11}$ | $0.199619373644 \mathrm{E}-8$ | $-0.228511870199 \mathrm{E}-5$ | $0.906310344601 \mathrm{E}-6$ |
| $A_{12}$ | $0.649999927290 \mathrm{E}-10$ | $0.210237043064 \mathrm{E}-5$ | $0.163513053801 \mathrm{E}-1$ |
| $A_{13}$ | $0.445903971647 \mathrm{E}-10$ | $-0.297437291704 \mathrm{E}-6$ | $0.182232225575 \mathrm{E}-5$ |
| $A_{14}$ | $0.277474320169 \mathrm{E}-11$ | $-0.657893753635 \mathrm{E}-5$ | $-0.289728555589 \mathrm{E}-4$ |
| $A_{15}$ | $-0.299587599489 \mathrm{E}-12$ | $-0.586867940003 \mathrm{E}-8$ | $0.563888239769 \mathrm{E}-5$ |
| $A_{16}$ | $-0.781397215670 \mathrm{E}-15$ | $-0.182883419201 \mathrm{E}-6$ | $0.254487597637 \mathrm{E}-3$ |

In particular, for period $8 \pi$ orbits, we have used $n_{\max }=36$ and for period $16 \pi$ orbits $n_{\max }=56$, which guarantee an accuracy better that $10^{-8}$ and $10^{-6}$, respectively, for the location of these orbits in phase space, at all $t$.

## 4. The Computation of Universal Constants

As we saw in the previous sections, the accuracy of the computation of periodic orbits near their bifurcation points is indeed a delicate matter. In a period-doubling sequence, like the one we have followed in this paper, several solutions of Eq. (3.9) can exist, very close to each other, for the same $v_{r}$ values.

Moreover, at higher and higher periods, more and more coefficients $A_{n}$ (and consequently larger and larger determinants in (2.16)) must be calculated to permit a highly accurate computation of the periodic orbits and their bifurcation values. Thus, after obtaining the period $8 \pi$ orbits on a modest UNIVAC $1100 / 60$, we use a supercomputer IBM- 3090600 E for our remaining calculations of the orbits of period $16 \pi$.

These accurate results were first used to determine to 12 -digit precision the bifurcation values $q_{4}$ and $q_{5}$ at which the orbts of period $16 \pi$ and $32 \pi$, respectively, first appear:

$$
\begin{equation*}
q_{4}=0.528089535489, \quad q_{5}=0.528124936353 \tag{4.1}
\end{equation*}
$$

Denoting then by $\delta$ the rate at which these values tend to their limit $q_{\infty}$, i.e.,

$$
\begin{equation*}
q_{k}-q_{\infty} \propto \delta^{-k}, \quad k \text { large } \tag{4.2}
\end{equation*}
$$

we compute the ratios

$$
\begin{equation*}
\delta_{k}=\left(q_{k}-q_{k+1}\right) /\left(q_{k+1}-q_{k+2}\right) \tag{4.3}
\end{equation*}
$$

for $k=1,2,3$, using the numbers listed in (2.3), (2.4), (2.8), and (4.1) above, and find

$$
\begin{aligned}
& \delta_{1}=8.88226488910 \\
& \delta_{2}=8.76320985647 \\
& \delta_{3}=8.72185249490
\end{aligned}
$$

This sequence indeed appears to indicate that, as $k$ increases, the $\delta_{k}$ 's quickly tend to the universal value $\delta=8.72109720 \ldots$, as expected from other studies on similar conservative systems [11, 12].

There are two more universal constants associated with period-doubling bifurcations of our Eq. (2.1). They correspond to scaling properties of these orbits and are computed as follows:

Denote by $d_{k}$ the distance between the two points of the period $2^{k}$ orbit, which lie on the $x$-axis of the Poincare surface of section (see Table II), at the $q=q_{k}$ value of its bifurcation to an orbit of twice the period. It is expected, from other similar studies that

$$
\begin{equation*}
\alpha_{k}=d_{k} / d_{k+1} \xrightarrow[k \rightarrow \infty]{ } \alpha=4.0180767 \ldots \tag{4.4}
\end{equation*}
$$

where this value value of $\alpha$ is universal for conservative two-degree of freedom Hamiltonian systems. From our results on the nonlinear Mathieu equation (2.1) we compute

$$
\begin{aligned}
& \alpha_{1}=d_{1} / d_{2}=4.0219742866 \\
& \alpha_{2}=d_{2} / d_{3}=4.0182210698
\end{aligned}
$$

which indeed appear to tend rather quickly to the universal value (4.4).
The universality of the above two constants $\alpha, \delta$ (with different values than were found above) was first observed for dissipative systems, whose dynamics is one-dimensional [13]. In the case of conservative systems, on the other hand (like area-preserving mappings in the plane), a third universal constant was found, corresponding to scaling of the orbits in a direction vertical to their axis of symmetry (for our nonlinear Mathieu equation, this is the $x$-axis of the surface of section).

This third constant, $\beta$, was incorporated by MacKay--together with the $\alpha$ of

TABLE II*
Surface of Section Intersections of Periodic Orbits


* The numbers listed in this section (and on Table I) have been rounded off. They are known to several more digits than is shown here.
(4.4) in a renormalization analysis of period-doubling in such two-dimensional systems [12] and was found to have the value

$$
\begin{equation*}
\beta=16.363896879 \ldots \tag{4.5}
\end{equation*}
$$

Our equation (2.1) also belongs to this class, since its dynamics can be represented by a locally arca-prescrving Poincarć map on its surface of Scetion (2.2) [4].

We have thus denoted by $b_{k}$, at the $q=q_{k}$ value where the period $2^{k+1}$ orbit is born, the distance between the two points of the period $2^{k}$ orbit, that had split off the $x$-axis at the previous bifurcation, and computed, using Table II,

$$
\begin{aligned}
& \beta_{1}=b_{1} / b_{2}=16.2611705 \\
& \beta_{2}=b_{2} / b_{3}=16.4124209
\end{aligned}
$$

These values again appear to approach the universal rate (4.5).

## 5. Concluding Remarks

We have described a numerical method for accurately computing the Fourier coefficients of periodic orbits of dynamical systems, which we have called the NSORB method (nonlinear successive overrelaxation bisection). This method complements the usual variational-iterative schemes for such orbits in that it improves their convergence near bifurcation points.

We have applied NSORB here to a period-doubling sequence of periodic solutions of a conservative nonlinear Mathieu equation (2.1) and have succeeded in overcoming the difficulties of previous schemes, and determining (to any desired accuracy) the first few bifurcations of period $2^{k}$ orbits $k=1,2,3, \ldots$.

As a result, we have been able to compute the first few approximations of the universal constants $\alpha, \beta$, and $\delta$ and found that they quickly tend to their expected values for this class of problems. These values have been long known from work on are-preserving mappings, but have not been as often (and as accurately) computed for conservative differential equations, due to serious difficulties of numerical precision.

Of course, we could apply the NSORB scheme to higher order period doubling bifurcations and calculate even better approximations to the universal constants of this paper, obtaining more digits of the numbers known already from areapreserving maps. Instead, we prefer to turn our attention, in future publications, to other problems of bifurcations of periodic orbits in dynamical systems.

In more than two degrees of freedom Hamiltonian systems, for example, the results are a lot more sporadic and their generality far are from being established. Infinite period-doubling sequences have apparently been observed only within one somewhat restricted class of conservative 4 -dimensional mappings [15]. Using NSORB we could follow period-doubling sequences in simple three-degrees of freedom models and see whether they always terminate after a small number of bifurcations as some other researchers have suggested [14].

Finally, since by the NSORB approach, problems of small divisors [4] do not arise, it might be possible to use it to calculate the Fourier coefficients $A_{m, n}$ of quasiperiodic orbits, for which the rotation number $\sigma$, cf. $(2,6)$, is irrational. Then, from the behavior of these $A_{m, n}$, as a function of some parameter of the equations, one could study the convergence properties of the series expansion of the solution and from that the "break up" of quasiperiodic orbits, when these series begin to diverge [26].

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